

On the Geometry of Noncommutative Deformations

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Outline

- Origin of the problem
- Basic tools
- Hawkins's Result
- Fundamental example
- Problem
- Solution

Origin of the problem : [Hawkins, J. Diff. Geom. 77 (2007) 385-424]

Let \mathcal{A}_0 be an algebra. A deformation in the sense of Hawkins of \mathcal{A}_0 is an extension of \mathcal{A}_0 of the form

$$0 \longrightarrow \hbar\mathcal{A} \longrightarrow \mathcal{A} \xrightarrow{P} \mathcal{A}_0 \longrightarrow 0,$$

where \hbar is central in \mathcal{A} and for any $a \in \mathcal{A}$

$$\hbar a = 0 \implies a = 0.$$

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Example

Fix $a \in \mathbb{C}$. Take $\mathcal{A}_0 = \mathbb{C}$, $\mathcal{A} = \mathbb{C}[X]$, $\hbar = (X - a)$ and $P(Q) = Q(a)$.

Example

$\mathcal{A}_0 = C^\infty(M, \mathbb{C})$ and

$$\mathcal{A} := \left\{ \sum_{n \geq 0} f_n \hbar^n, f_n \in \mathcal{A}_0 \right\}$$

a \star -product¹ on \mathcal{A} given by, $f, g \in \mathcal{A}_0 \subset \mathcal{A}$,

$$f \star g = fg + \sum_{n \geq 1} B_n(f, g) \hbar^n$$

and $P : \mathcal{A} \rightarrow \mathcal{A}_0$ given by

$$P \left(\sum_{n \geq 0} f_n \hbar^n \right) = f_0.$$

1. By virtue of a famous theorem of Kontsevich such a \star -product exists. 

Let $(\Omega^*(M), \wedge, d)$ be the graded algebra of differential forms on a manifold M and

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a **deformation** of $\Omega^*(M)$ in the sense of Hawkins. Consider the bracket

$$\{\mathcal{P}(\alpha), \mathcal{P}(\beta)\} = \mathcal{P}\left(\frac{1}{\hbar}[\alpha, \beta]\right), \quad \alpha, \beta \in \mathcal{A}$$

where

$$[\alpha, \beta] = \alpha.\beta - (-1)^{\deg\alpha\deg\beta}\beta.\alpha$$

is the graded commutator in \mathcal{A} .

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$$\pi(df, dg) := \{f, g\} \quad \text{and} \quad \mathcal{D}_{df}\alpha := \{f, \alpha\}, \quad f, g \in C^\infty(M), \alpha \in \Omega^1(M).$$

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The triple (M, π, \mathcal{D}) constitutes the geometry of the deformation of $\Omega^*(M)$.

Deformation of the spectral triple associated to a Riemannian manifold

Let (M, g) be a Riemannian manifold. Any deformation of the **spectral triple**² of (M, g) induces a deformation of $\Omega^*(M)$ and hence, gives rise to a Poisson tensor π and a contravariant connexion \mathcal{D} satisfying the conditions above.

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2. (Hilbert space, an algebra, unbounded self-adjoint operator).

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(M, g, π, \mathcal{D}) is **the geometry of the deformation of the spectral triple associated to (M, g)** .

Poisson manifolds

DEFINITION

A *Poisson bracket* on M is

$$\{\cdot, \cdot\} : C^\infty(M) \times C^\infty(M) \rightarrow C^\infty(M)$$

- \mathbb{R} -bilinear
- $\{f, g\} = -\{g, f\}$ (anti-symmetric)
- $\{f, \{g, h\}\} + \{g, \{h, f\}\} + \{h, \{f, g\}\} = 0$ (Jacobi)
- $\{f, gh\} = g\{f, h\} + h\{f, g\}$ (Leibniz)

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EXAMPLES

- ▶ Every symplectic manifold $(M, \omega) : \{f, g\} := \omega(X_f, X_g)$.
- ▶ The dual of a Lie algebra $(\mathfrak{g}, [\cdot, \cdot]) :$
$$\{f, g\}(a) := \langle a, [d_a f, d_a g] \rangle \quad (a \in \mathfrak{g}^*, f, g \in C^\infty(\mathfrak{g}^*)).$$

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A Poisson bracket defines :

- a bivector field $\pi \in \Gamma(\wedge^2 TM) : \pi(df, dg) := \{f, g\}$. Jacobi
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 - The open set $M^{\text{reg}} = \{\text{points où } \rho_{\pi} \text{ locally constant}\}$ is dense in M ; a point in M^{reg} is called *regular*.
- a Lie bracket on $\Omega^1(M)$, called *de Koszul's bracket* :

$$[\alpha, \beta]_{\pi} := L_{\pi_{\#}(\alpha)}\beta - L_{\pi_{\#}(\beta)}\alpha - d(\pi(\alpha, \beta)).$$

Contravariant connections

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A *contravariant connection* on (M, π) is

$$\mathcal{D} : \Omega^1(M) \times \Omega^1(M) \rightarrow \Omega^1(M), \text{ notée } (\alpha, \beta) \mapsto \mathcal{D}_\alpha \beta,$$

\mathbb{R} -bilinear and satisfying

$$\mathcal{D}_f \alpha \beta = f \mathcal{D}_\alpha \beta, \quad \mathcal{D}_\alpha (f\beta) = f \mathcal{D}_\alpha \beta + \pi_\#(\alpha)(f)\beta \quad (f \in \mathcal{C}^\infty(M)).$$

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The *torsion* and the *curvature* of \mathcal{D} are :

$$T(\alpha, \beta) := \mathcal{D}_\alpha \beta - \mathcal{D}_\beta \alpha - [\alpha, \beta]_\pi,$$

$$R(\alpha, \beta)\gamma := \mathcal{D}_\alpha \mathcal{D}_\beta \gamma - \mathcal{D}_\beta \mathcal{D}_\alpha \gamma - \mathcal{D}_{[\alpha, \beta]_\pi} \gamma.$$

When $T = 0$ (resp. $R = 0$), \mathcal{D} is called *torsionless* (resp. *flat*).

Contravariant connexion

FUNDAMENTAL EXAMPLE

Given a Riemannian metric g on (M, π) , $\exists!$ contravariant connection \mathcal{D} of (M, π) such that $T = 0$ et $\mathcal{D}g = 0$; it is given by:

$$\langle \mathcal{D}_\alpha \beta, \gamma \rangle = \frac{1}{2} \{ \pi_\#(\alpha) \cdot \langle \beta, \gamma \rangle + \pi_\#(\beta) \cdot \langle \alpha, \gamma \rangle - \pi_\#(\gamma) \cdot \langle \alpha, \beta \rangle \\ + \langle [\alpha, \beta]_\pi, \gamma \rangle - \langle [\beta, \gamma]_\pi, \alpha \rangle + \langle [\gamma, \alpha]_\pi, \beta \rangle \}$$

and called *the Levi-Civita contravariant connection* associated to (π, g) (in short : *CLCC*).

Metacurvature ?

HAWKINS'S BRACKET

If \mathcal{D} is a contravariant connection torsionless on (M, π) ,

$$\exists! \{ \cdot, \cdot \} : \Omega^*(M) \times \Omega^*(M) \longrightarrow \Omega^*(M)$$

- \mathbb{R} -bilinear,
- degree 0 : $\deg \{ \sigma, \tau \} = \deg \sigma + \deg \tau$,
- graded commutative : $\{ \sigma, \tau \} = -(-1)^{\deg \sigma \deg \tau} \{ \tau, \sigma \}$,
- Leibniz : $\{ \sigma, \tau \wedge \rho \} = \{ \sigma, \tau \} \wedge \rho + (-1)^{\deg \sigma \deg \tau} \tau \wedge \{ \sigma, \rho \}$,
- derivation : $d \{ \sigma, \tau \} = \{ d\sigma, \tau \} + (-1)^{\deg \sigma} \{ \sigma, d\tau \}$,
- For any $f, g \in C^\infty(M)$ and any $\alpha \in \Omega^1(M)$,

$$\{ f, g \} = \pi(df, dg), \quad \{ f, \alpha \} = \mathcal{D}_f \alpha.$$

Metacurvature ?

JACOBI IDENTITY AND METACURVATURE

What about the Jacobi identity,

$$\{\sigma, \{\tau, \rho\}\} - \{\{\sigma, \tau\}, \rho\} - (-1)^{\deg \sigma \deg \tau} \{\tau, \{\sigma, \rho\}\} = 0 ?$$

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In low degrees, we have :

- $\mathcal{J}(f, g, h) = 0$ since π is Poisson.
- $\mathcal{J}(f, g, \alpha) = \mathcal{D}_{df} \mathcal{D}_{dg} \alpha - \mathcal{D}_{d\{f, g\}} \alpha - \mathcal{D}_{dg} \mathcal{D}_{df} \alpha = R(df, dg) \alpha$.
- If \mathcal{D} is flat then the formula

$$\mathcal{M}(df, \alpha, \beta) := \mathcal{J}(f, \alpha, \beta) = \{f, \{\alpha, \beta\}\} - \{\{f, \alpha\}, \beta\} - \{\{f, \beta\}, \alpha\}$$

where $\alpha, \beta \in \Omega^1(M)$ defines a tensor field \mathcal{M} of type $(2, 3)$.

Proposition

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One can see \mathcal{M} as an element of $\Gamma(S^3TM \otimes \wedge^2T^*M)$.

Computation of Hawkins's bracket and the metacurvature

Let (M, π, \mathcal{D}) be a manifold endowed with a Poisson tensor and a contravariant connexion torsionless and flat. The Hawkins's bracket in low degrees is given by

$$\{f, g\} = \pi(df, dg), \quad \{f, \alpha\} = \mathcal{D}_{df}\alpha, \quad f, g \in C^\infty(M), \quad \alpha \in \Omega^1(M).$$

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The metacurvature is given

$$\mathcal{M}(df, \alpha, \beta) = \{f, \{\alpha, \beta\}\} - \{\{f, \alpha\}, \beta\} - \{\alpha, \{f, \beta\}\}, \quad f \in C^\infty(M), \quad \alpha, \beta \in \Omega^1(M).$$

Important Remark

If α is parallel, i.e., $\mathcal{D}\alpha = 0$, for any $\beta \in \Omega^1(M)$,

$$\boxed{\{\alpha, \beta\} = -\mathcal{D}_\beta d\alpha.} \quad (1)$$

Important Remark

If α is parallel, i.e., $\mathcal{D}\alpha = 0$, for any $\beta \in \Omega^1(M)$,

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If α and β are parallel, for any $\gamma \in \Omega^1(M)$,

$$\boxed{\mathcal{M}(\alpha, \beta, \gamma) = -\mathcal{D}_\gamma \mathcal{D}_\beta d\alpha.} \quad (2)$$

Back to the initial problem

If (M, g) is a Riemannian manifold,

[A deformation of the spectrale triple of (M, g)]



[\exists a Poisson tensor π on M such that :
(H_1) The CLCC \mathcal{D} associatied to (π, g) is flat
(H_2) The metacurvature of \mathcal{D} vanishes
(H_3) $d(i_\pi \mu) = 0$, where μ is the Riemannian volume]

Main result of Hawkins

Theorem 1 [Hawkins, J. Diff. Geom. 77 (2007) 385-424]

Let (M, π) be a Poisson manifold endowed with a Riemannian metric g . Assume that M is compact satisfying (H_1) , (H_2) and (H_3) . Then, near any $x \in M^{reg}$,

$$\pi = \frac{1}{2} \sum_{i,j} a_{ij} X_i \wedge X_j$$

where (a_{ij}) is constant and invertible and X_1, \dots, X_{2r} are linearly independent commuting Killing vector fields. Moreover, $\mathcal{D}\pi = 0$.³.

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- of Poisson manifolds (M, π) endowed with a contravariant connection \mathcal{D} such the torsion, the curvature and the metacurvature of \mathcal{D} vanish.
- of Poisson manifold (M, g, π) endowed with a Riemannian metric such that the Levi-Civita contravariant connection associated à (π, g) is flat and metaflat.

Fundamental Example

Let

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and $\mathcal{D}^r : \Omega^1(M) \times \Omega^1(M) \rightarrow \Omega^1(M)$,

$$(\alpha, \beta) \mapsto \mathcal{D}_\alpha^r \beta := \sum_{i,j} a_{ij} \alpha(\zeta(u_i)) \mathcal{L}_{\zeta(u_j)} \beta$$

where $r = \sum a_{ij} u_i \wedge u_j$ and $\{u_1, \dots, u_n\}$ is a basis of \mathfrak{g} .

Fundamental Example

Theorem 2 [Boucetta, Lett. Math. Phys. 83 (2008) 69-81]

- (a) π^r and \mathcal{D}^r depend only on r and ζ and define, respectively, a Poisson tensor and a contravariant connection **torsionless and flat** on M .
- (b) If g is a Riemannian metric on M and ζ preserves g , i.e., for any $u \in \mathfrak{g}$, $\zeta(u)$ is a Killing vector field, then \mathcal{D}^r is the contravariant Levi-Civita connection of (π^r, g) .
- (c) If ζ is **free**, i.e., for any $x \in M$, the map $v \mapsto \zeta(v)(x)$ is injective then the metacurvature of \mathcal{D}^r vanishes.

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Remark. In (c), we cannot drop the hypothesis ζ free.

The problem ?

Given a Poisson manifold (M, π) endowed with a contravariant connection without torsion, flat and metaflat, for any regular point x there exists a neighborhood U of x , a free action of a finite dimensional Lie algebra $\zeta : \mathfrak{g} \rightarrow \mathfrak{X}(U)$, and a solution $r \in \wedge^2 \mathfrak{g}$ of CYBE such that $\pi|_U = \pi^r$ and $\mathcal{D} = \mathcal{D}^r$?

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- In the fundamental example, if ζ is free then it is \mathbf{T} which vanishes implying the vanishing of the metacurvature.

The problem reformulated :

Given a Poisson manifold (M, π) endowed with a \mathcal{F}^{reg} -contravariant connection without torsion, flat and $\mathbf{T} = 0$, for any regular point x there exists a neighborhood U of x , a free action of a finite dimensional Lie algebra $\zeta : \mathfrak{g} \rightarrow \mathfrak{X}(U)$, and a solution $r \in \wedge^2 \mathfrak{g}$ of CYBE such that $\pi|_U = \pi^r$ and $\mathcal{D} = \mathcal{D}^r$?

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Moreover, if \mathcal{D} is the Levi-Civita contravariant connection of (M, π, g) , the action ζ preserves g ?

Solution : Main result

Théorème 3 [Boucetta & Saassai, J. Geom. Phys. 82 (2014) 64-74]

Let (M, π, \mathcal{D}) be a Poisson manifold endowed with a contravariant connection torsionless and flat.

- If \mathcal{D} is a \mathcal{F}^{reg} -connection and $\mathbf{T} = 0$, then for any $x_0 \in M^{reg}$ there exists a neighborhood U of x , a free action of a finite dimensional Lie algebra $\zeta : \mathfrak{g} \rightarrow \mathfrak{X}(U)$, and an invertible solution $r \in \Lambda^2 \mathfrak{g}$ of CYBE such that $\pi|_U = \pi^r$ and $\mathcal{D} = \mathcal{D}^r$.
- Moreover, if \mathcal{D} is the Levi-Civita contravariant connection of (M, π, g) then the action ζ preserves g .

Solution : Building a flat co-frame

Let (M, π, \mathcal{D}) such that \mathcal{D} is a \mathcal{F}^{reg} -connection, torsionless and flat. Let $x_0 \in M^{reg}$ and (a_1, \dots, a_{2r}) a family of covectors in $T_{x_0}^* M$ such that $(\pi_{\#}(a_1), \dots, \pi_{\#}(a_{2r}))$ is a basis of $\text{Im} \pi_{\#}(x_0)$.

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- For any $a \in T_{x_0}^*M$, there exists an open set $U \ni x_0$ and $\beta^a \in \Omega^1(U)$ such that $\beta^a(x_0) = a$ and $\mathcal{D}\beta^a = 0$.

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- Note $\phi_i = \beta^{a_i}$. The vector fields $(\pi_{\#}(\phi_1), \dots, \pi_{\#}(\phi_{2r}))$ are commuting linearly independent so there exists a coordinates system $((x^i)_{i=1}^{2r}, (y^j)_{j=1}^{d-2r})$ such that $\pi_{\#}(\phi_i) = \frac{\partial}{\partial x^i}$, $i = 1, \dots, 2r$.

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- For any $x \in U$, put $\mathcal{H}_x = \text{vect}\{\phi_1(x), \dots, \phi_{2r}(x)\}$. We have $T_U^*M = \ker \pi_{\#} \oplus \mathcal{H}$ and $\mathcal{D}\mathcal{H} \subset \mathcal{H}$.

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- $\mathbf{F}^* = \{\phi_1, \dots, \phi_{2r}, dy^1, \dots, dy^{d-2r}\}$ is a flat co-frame.

Solution : The frame dual of F^*

For any $i = 1, \dots, 2r$, there exists a unique family of functions A_i^1, \dots, A_i^s such that $dx^i + \sum_u A_i^u dy_u \in \mathcal{H}$. Consider

$$X^i := -X_{x^i} = -\pi_{\sharp}(dx^i), \quad Y_u := \frac{\partial}{\partial y_u} - \sum_{i=1}^{2r} A_i^u \frac{\partial}{\partial x^i}.$$

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Lemma 3

$\{X_i, Y_u\}$ is the dual frame of \mathbf{F}^* . Moreover, the vector fields X_i and Y_u are, respectively, Hamiltonian and Poisson, and satisfy :

$$\begin{aligned} [X_i, X_j] &= - \sum_{k=1}^{2r} \frac{\partial \pi_{ij}}{\partial x_k} X_k; & [X_i, Y_u] &= \sum_{j=1}^{2r} \frac{\partial A_i^u}{\partial x_j} X_j; \\ [Y_u, Y_v] &= \sum_{i,j=1}^{2r} \pi^{ij} \left(\frac{\partial A_j^u}{\partial y_v} - \frac{\partial A_j^v}{\partial y_u} + \sum_{k=1}^{2r} A_k^u \frac{\partial A_j^v}{\partial x_k} - A_k^v \frac{\partial A_j^u}{\partial x_k} \right) X_i. \end{aligned}$$

with $(\pi_{ij}) = (\pi(dx^i, dx^j))$ and (π^{ij}) is the inverse of the matrix (π_{ij}) .

Solution : The tensor fields \mathcal{M} et \mathbf{T}

Theorem 4

■ For any u , $\mathcal{M}(dy_u, \cdot, \cdot) = 0$.

■ For any i, j, k ,

$$\begin{aligned} \mathcal{M}(\phi_i, \phi_j, \phi_k) &= - \sum_{l < m} \frac{\partial^3 \pi_{lm}}{\partial x_i \partial x_j \partial x_k} \phi_l \wedge \phi_m + \sum_{l, u} \frac{\partial^3 A_l^u}{\partial x_i \partial x_j \partial x_k} \phi_l \wedge dy_u \\ &+ \sum_{u < v, l} \frac{\partial^2}{\partial x_i \partial x_j} \left(\pi^{kl} \left(\frac{\partial A_l^u}{\partial y_v} - \frac{\partial A_l^v}{\partial y_u} + \sum_m A_m^u \frac{\partial A_l^v}{\partial x_m} - A_m^v \frac{\partial A_l^u}{\partial x_m} \right) \right) dy_u \wedge dy_v. \end{aligned}$$

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Theorem 5

- For any u , $\mathbf{T}(dy_u, \cdot) = 0$.
- For any i, j ,

$$\begin{aligned} \mathbf{T}(\phi_i, \phi_j) &= - \sum_{k < l} \frac{\partial^2 \pi_{kl}}{\partial x_i \partial x_j} \phi_k \wedge \phi_l + \sum_{k, u} \frac{\partial^2 A_k^u}{\partial x_i \partial x_j} \phi_k \wedge dy_u \\ &+ \sum_{u < v, k} \frac{\partial}{\partial x_i} \left(\pi^{jk} \left(\frac{\partial A_k^u}{\partial y_v} - \frac{\partial A_k^v}{\partial y_u} + \sum_l A_l^u \frac{\partial A_k^v}{\partial x_l} - A_l^v \frac{\partial A_k^u}{\partial x_l} \right) \right) dy_u \wedge dy_v. \end{aligned}$$

Solution : Proof of Theorem 3

SKETCH OF THE PROOF

The idea is to build near x_0 a family of linearly independent vector fields $Z_1, \dots, Z_{2r} \in \Gamma(\mathcal{C})$ which commute with X_i and Y_u . In this case

- $[Z_i, Z_j] = \sum_k c_{ij}^k Z_k$ with $c_{ij}^k = cst$ hence Z_1, \dots, Z_{2r} generate a Lie algebra of dimension $2r$ which acts freely near x_0 .
- $\pi = \frac{1}{2} \sum_{i,j} a_{ij} Z_i \wedge Z_j$ where (a_{ij}) is constant and invertible.
- $\mathcal{D}_\alpha \beta = \sum_{i,j} a_{ij} \alpha(Z_i) \mathcal{L}_{Z_j} \beta$; indeed, this is true for $\beta = \phi_i$ or dy_u since $\mathcal{L}_{Z_i} \phi_j = \mathcal{L}_{Z_i} dy_u = 0$. And $\mathcal{D}_\alpha \beta - \sum_{i,j} a_{ij} \alpha(Z_i) \mathcal{L}_{Z_j} \beta$ is tensorial in β .

Solution : Proof of Theorem 3

We proceed on two steps :

FIRST STEP

We build a family of vector fields $T_1, \dots, T_{2r} \in \Gamma(\mathcal{C})$ which commute with the X_i . Indeed, the vanishing of \mathbf{T} and Lemma 3, imply :

$$[X_i, X_j] = \sum_{k=1}^{2r} \lambda_{ij}^k X_k, \quad [X_i, Y_u] = \sum_{j=1}^{2r} \mu_{iu}^j X_j, \quad [Y_u, Y_v] = \sum_{i=1}^{2r} \nu_{uv}^i X_i$$

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We choose a transversal \mathcal{T} to the symplectic foliation \mathcal{S} passing through x_0 . For $y \in \mathcal{T}$ fix, $X_{1|_{\mathcal{S}_y}}, \dots, X_{2r|_{\mathcal{S}_y}}$ span a Lie algebra \mathfrak{g}_y which act freely and transitively on \mathcal{S}_y , so \exists an anti-homomorphism of Lie algebras $\Gamma_y : \mathfrak{g}_y \rightarrow \mathfrak{X}^1(\mathcal{S}_y)$, such that

$$\Gamma_y(X_{i|_{\mathcal{S}_y}})(y) = X_i(y), \quad [\Gamma_y(X_{i|_{\mathcal{S}_y}}), X_{j|_{\mathcal{S}_y}}] = 0 \quad \forall i, j.$$

We take $T_i(z) := \Gamma_y(X_i^y)(z)$, $z \in \mathcal{S}_y$ and we variate y to obtain T_i .

Solution : Proof of Theorem 3

Now, the μ_{iu}^j are Casimir

$$[T_i, Y_u] = \sum_{j=1}^{2r} \gamma_{iu}^j T_j$$

with γ_{iu}^j Casimir and satisfy

$$\frac{\partial \gamma_{ju}^i}{\partial y_v} - \frac{\partial \gamma_{jv}^i}{\partial y_u} + \sum_{k=1}^{2r} \gamma_{ku}^i \gamma_{jv}^k - \gamma_{kv}^i \gamma_{ju}^k = 0 \quad (*)$$

since the ν_{uv}^i are Casimir and $[T_i, [Y_u, Y_v]] = 0$ for any i, u, v .

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since the ν_{uv}^i are Casimir and $[T_i, [Y_u, Y_v]] = 0$ for any i, u, v .

SECOND STEP

We look for the Z_i in the form :

$$Z_i := \sum_{j=1}^{2r} \xi_{ji} T_j$$

where ξ_{ij} are Casimir and $\xi = (\xi_{ij})$ is invertible. They exist by virtue of (*).

Thank you