

Einstein Lorentzian Nilpotent Lie groups

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Seminar Algebra, Geometry, Topology and Applications

Outline

- 1 Preliminaries
- 2 Ricci curvature of left invariant pseudo-Riemannian metric
- 3 Some results on Einstein Lorentzian nilpotent Lie algebras
- 4 Einstein Lorentzian nilpotent Lie algebras with degenerate center are obtained by the double extension process

A *pseudo-Euclidean vector space* is a real vector space of finite dimension n endowed with a nondegenerate symmetric inner product of signature $(q, n - q) = (- \dots -, + \dots +)$.

When the signature is $(0, n)$ (resp. $(1, n - 1)$) the space is called *Euclidean* (resp. *Lorentzian*).

Let $(V, \langle \cdot, \cdot \rangle)$ be a pseudo-Euclidean vector space of signature $(q, n - q)$. A vector $u \in V$ is called:

- 1 *spacelike* if $\langle u, u \rangle > 0$,
- 2 *timelike* if $\langle u, u \rangle < 0$ and
- 3 *isotropic* if $\langle u, u \rangle = 0$.

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A subspace F of a pseudo-Euclidean vector space $(V, \langle \cdot, \cdot \rangle)$ is called:

- 1 Nondegenerate if $F \cap F^\perp = \{0\}$,
- 2 degenerate if $F \cap F^\perp \neq \{0\}$,
- 3 Isotropic if $\langle u, v \rangle = 0$ for any $u, v \in F$.

Note that we have always $\dim F + \dim F^\perp = \dim V$.

If F is isotropic then $\dim F \leq \min(q, n - q)$.

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A family (u_1, \dots, u_s) of vectors in V is called *orthogonal* if, for $i, j = 1, \dots, s$ and $i \neq j$, $\langle u_i, u_j \rangle = 0$.

An orthonormal basis of V is an orthogonal basis (e_1, \dots, e_n) such that $\langle e_i, e_i \rangle = \pm 1$.

A *pseudo-Euclidean basis* of V is a basis $(e_1, \bar{e}_2, \dots, e_q, \bar{e}_q, f_1, \dots, f_{n-2q})$ for which the non vanishing products are $\langle \bar{e}_i, e_i \rangle = \langle f_j, f_j \rangle = 1$, $i \in \{1, \dots, q\}$ and $j \in \{1, \dots, n - 2q\}$. When V is Lorentzian, we call such a basis *Lorentzian*.

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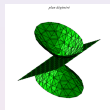
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Let $(V, \langle \cdot, \cdot \rangle)$ be Lorentzian vector space and $F \subset V$ is a vector subspace. Then either:

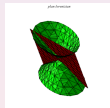
- 1 F is nondegenerate Euclidean and F^\perp is nondegenerate Lorentzian,
- 2 F is nondegenerate Lorentzian and F^\perp is nondegenerate Euclidean,
- 3 F is degenerate and $\dim(F \cap F^\perp) = 1$.

Preliminaries

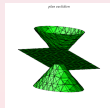
Ricci curvature of left invariant pseudo-Riemannian metric
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A degenerate plan.



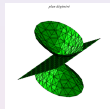
A Lorentzian plan.



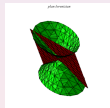
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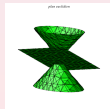
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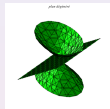
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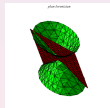
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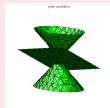
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For any endomorphism $F : V \longrightarrow V$, we denote by $F^* : V \longrightarrow V$ its adjoint with respect to $\langle \cdot, \cdot \rangle$. The following lemma will be useful later.

Lemma

Let $(V, \langle \cdot, \cdot \rangle)$ be a Lorentzian vector space, e an isotropic vector and J a skew-symmetric endomorphism. Then $\langle Je, Je \rangle \geq 0$. Moreover, $\langle Je, Je \rangle = 0$ if and only if $Je = \alpha e$.

Proof.

We choose an isotropic vector \bar{e} such that $\langle e, \bar{e} \rangle = 1$ and an orthonormal basis (f_1, \dots, f_r) of $\{e, \bar{e}\}^\perp$. Since J is skew-symmetric then

$$Je = \alpha e + \sum_{i=1}^r a_i f_i \quad \text{and} \quad \langle Je, Je \rangle = \sum_{i=1}^r a_i^2.$$

This completes the proof. \square

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Let (G, g) be a Lie group endowed with a left-invariant pseudo-Riemannian metric. The study of the curvature of (G, g) is equivalent to the study of $(\mathfrak{g} = T_e G, [,], \langle , \rangle = g(e))$. We refer to $(\mathfrak{g}, [,], \langle , \rangle)$ as a pseudo-Euclidean Lie algebra. Levi-Civita connection of (G, g) defines a product $L : \mathfrak{g} \times \mathfrak{g} \longrightarrow \mathfrak{g}$ called *Levi-Civita product* given by Koszul's formula

$$2\langle L_u v, w \rangle = \langle [u, v], w \rangle + \langle [w, u], v \rangle + \langle [w, v], u \rangle. \quad (1)$$

For any $u, v \in \mathfrak{g}$, $L_u : \mathfrak{g} \longrightarrow \mathfrak{g}$ is skew-symmetric and $[u, v] = L_u v - L_v u$.

We denote by $R_u : \mathfrak{g} \longrightarrow \mathfrak{g}$, the right multiplication $R_u(v) = L_v u$.

We have $L_u - R_u = \text{ad}_u$.

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The curvature of \mathfrak{g} is given by

$$\begin{aligned} K(u, v)w &= L_{[u, v]}w - [L_u, L_v]w \\ &= [R_w, L_u](v) - R_w \circ R_u(v) + R_{uv}(v). \end{aligned}$$

The Ricci curvature $\text{ric} : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathbb{R}$ and its Ricci operator $\text{Ric} : \mathfrak{g} \rightarrow \mathfrak{g}$ are defined by

$$\begin{aligned} \langle \text{Ric}(u), v \rangle &= \text{ric}(u, v) = \text{tr}(w \rightarrow K(u, w)v) \\ &= -\text{tr}(R_w \circ R_u) + \text{tr}(R_{uv}). \end{aligned}$$

We have

$$\operatorname{tr}(\mathbb{R}_{uv}) = -\frac{1}{2} (\langle \operatorname{ad}_H u, v \rangle + \langle \operatorname{ad}_H v, u \rangle),$$

where H is the vector given by $\langle H, u \rangle = \operatorname{tr}(\operatorname{ad}_u)$.

One can deduce easily from (1) that

$$\mathbb{R}_u = -\frac{1}{2} (\operatorname{ad}_u + \operatorname{ad}_u^*) - \frac{1}{2} J_u,$$

where $J_u : \mathfrak{g} \longrightarrow \mathfrak{g}$ is the skew-symmetric the endomorphism given by $J_u(v) = \operatorname{ad}_v^* u$.

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Proposition

We have

$$\begin{aligned} \text{ric}(u, v) &= -\frac{1}{2}\text{tr}(\text{ad}_u \circ \text{ad}_v) - \frac{1}{2}\text{tr}(\text{ad}_u \circ \text{ad}_v^*) - \frac{1}{4}\text{tr}(J_u \circ J_v) \\ &\quad - \frac{1}{2}\langle \text{ad}_H u, v \rangle - \frac{1}{2}\langle \text{ad}_H v, u \rangle, \\ \langle H, u \rangle &= \text{tr}(\text{ad}_u), \\ J_u(v) &= \text{ad}_v^t(u). \quad (J_u = 0 \iff u \in [\mathfrak{g}, \mathfrak{g}]^\perp). \end{aligned}$$

Proposition

If \mathfrak{g} is nilpotent then

$$\begin{aligned} \text{ric}(u, v) &= -\frac{1}{2}\text{tr}(\text{ad}_u \circ \text{ad}_v^*) - \frac{1}{4}\text{tr}(J_u \circ J_v) \\ &= -\frac{1}{2}\langle \mathcal{J}_1(u), v \rangle + \frac{1}{4}\langle \mathcal{J}_2(u), v \rangle, \\ \text{Ric} &= -\frac{1}{2}\mathcal{J}_1 + \frac{1}{4}\mathcal{J}_2. \end{aligned}$$

Remark

If $\langle \cdot, \cdot \rangle$ is Euclidean then $\langle \mathcal{J}_1(u), u \rangle \geq 0$ (resp. $\langle \mathcal{J}_2(u), u \rangle \geq 0$) and $\langle \mathcal{J}_1(u), u \rangle = 0$ (resp. $\langle \mathcal{J}_2(u), u \rangle = 0$) if $u \in Z(\mathfrak{g})$ (resp. $u \in [\mathfrak{g}, \mathfrak{g}]^\perp$).

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Let (e_1, \dots, e_p) be a basis of \mathfrak{g} . Then, for any $u, v \in \mathfrak{g}$, the Lie bracket can be written

$$[u, v] = \sum_{i=1}^p \langle S_i u, v \rangle e_i, \quad (2)$$

where $S_i : \mathfrak{g} \rightarrow \mathfrak{g}$ are skew-symmetric endomorphisms with respect to $\langle \cdot, \cdot \rangle$.

The family (S_1, \dots, S_p) will be called *structure endomorphisms* associated to (e_1, \dots, e_p) .

We have $Z(\mathfrak{g}) = \bigcap_{i=1}^p \ker S_i$ and for any $u \in \mathfrak{g}$,

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Recall that if \mathfrak{g} is nilpotent

$$\begin{aligned} \text{ric}(u, v) &= -\frac{1}{2}\text{tr}(\text{ad}_u \circ \text{ad}_v^*) - \frac{1}{4}\text{tr}(J_u \circ J_v) \\ &= -\frac{1}{2}\langle \mathcal{J}_1(u), v \rangle + \frac{1}{4}\langle \mathcal{J}_2(u), v \rangle. \end{aligned}$$

Proposition

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be a pseudo-Euclidean Lie algebra, (e_1, \dots, e_p) a basis of \mathfrak{g} and (S_1, \dots, S_p) the corresponding structure endomorphisms. Then

$$\mathcal{J}_1 = -\sum_{i,j=1}^p \langle e_i, e_j \rangle S_i \circ S_j \quad \text{and} \quad \mathcal{J}_2 u = -\sum_{i,j=1}^p \langle e_i, u \rangle \text{tr}(S_i \circ S_j) e_j. \quad (4)$$

In particular, $\text{tr} \mathcal{J}_1 = \text{tr} \mathcal{J}_2$.

A pseudo-Euclidean Lie algebra $(\mathfrak{g}, [,], \langle , \rangle)$ is called Einstein if there exists a $\lambda \in \mathbb{R}$ such that

$$\text{Ric} = \lambda \text{Id}_{\mathfrak{g}}.$$

If $\lambda = 0$ then $(\mathfrak{g}, [,], \langle , \rangle)$ is called Ricci flat.

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A nilpotent pseudo-Euclidean Lie algebra $(\mathfrak{g}, [,], \langle , \rangle)$ is Einstein if there exists a $\lambda \in \mathbb{R}$ such that

$$-\frac{1}{2}\mathcal{J}_1 + \frac{1}{4}\mathcal{J}_2 = \lambda \text{Id}_{\mathfrak{g}}.$$

This is a very complicated quadratic equation and we will solve it for $\dim \mathfrak{g} \leq 5$.

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The following proposition appeared first in the Euclidean context.

Proposition

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be a pseudo-Euclidean Lie algebra and let Q denote the symmetric endomorphism $Q = -\frac{1}{2}\mathcal{J}_1 + \frac{1}{4}\mathcal{J}_2$. Then for any orthonormal basis (e_1, \dots, e_p) of \mathfrak{g} and any endomorphism E of \mathfrak{g} , we have

$$\operatorname{tr}(QE) = \frac{1}{4} \sum_{i,j} \varepsilon_i \varepsilon_j \langle E([e_i, e_j]) - [E(e_i), e_j] - [e_i, E(e_j)], [e_i, e_j] \rangle, \quad (5)$$

where $\langle e_i, e_i \rangle = \varepsilon_i$.

Proposition

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be a pseudo-Euclidean nilpotent Lie algebra having a derivation with non null trace. Then $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ is Einstein if and only if it is Ricci flat.

Remark

The Lie algebra of derivations of nilpotent Lie algebras has been widely studied and computed. It turns out that nilpotent Lie algebras having a derivation with non null trace are the most common. For instance, any nilpotent Lie algebra up to dimension 6 has this property.

Let $(\mathfrak{g}, [,], \langle , \rangle)$ be a pseudo-Euclidean Lie algebra. We have

$$Z(\mathfrak{g}) \subset M = \ker \mathcal{J}_1 \quad \text{and} \quad [\mathfrak{g}, \mathfrak{g}]^\perp \subset N = \ker \mathcal{J}_2.$$

Since \mathcal{J}_1 and \mathcal{J}_2 are symmetric

$$\text{Im} \mathcal{J}_1 = M^\perp \subset Z(\mathfrak{g})^\perp \quad \text{and} \quad \text{Im} \mathcal{J}_2 = N^\perp \subset [\mathfrak{g}, \mathfrak{g}].$$

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Suppose that $(\mathfrak{g}, [,], \langle , \rangle)$ is nilpotent and Einstein with $\lambda \neq 0$, i.e.,

$$-\frac{1}{2}\mathcal{J}_1 + \frac{1}{4}\mathcal{J}_2 = \lambda \text{Id}_{\mathfrak{g}}.$$

This implies

$$Z(\mathfrak{g}) \subset \text{Im}\mathcal{J}_2 \subset [\mathfrak{g}, \mathfrak{g}].$$

Moreover, $M \cap N = \{0\}$. If $\dim Z(\mathfrak{g}) \geq \dim[\mathfrak{g}, \mathfrak{g}]$ then

$$\dim M + \dim N \geq \dim Z(\mathfrak{g}) + \dim[\mathfrak{g}, \mathfrak{g}]^{\perp} \geq \dim \mathfrak{g}$$

and hence $\mathfrak{g} = M \oplus N$. This contradicts $\text{tr}(\mathcal{J}_1) = \text{tr}(\mathcal{J}_2)$.

Suppose that $(\mathfrak{g}, [,], \langle , \rangle)$ is nilpotent and Einstein with $\lambda \neq 0$, i.e.,

$$-\frac{1}{2}\mathcal{J}_1 + \frac{1}{4}\mathcal{J}_2 = \lambda \text{Id}_{\mathfrak{g}}.$$

This implies

$$Z(\mathfrak{g}) \subset \text{Im}\mathcal{J}_2 \subset [\mathfrak{g}, \mathfrak{g}].$$

Moreover, $M \cap N = \{0\}$. If $\dim Z(\mathfrak{g}) \geq \dim[\mathfrak{g}, \mathfrak{g}]$ then

$$\dim M + \dim N \geq \dim Z(\mathfrak{g}) + \dim[\mathfrak{g}, \mathfrak{g}]^{\perp} \geq \dim \mathfrak{g}$$

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Proposition

Let $(\mathfrak{g}, [,], \langle , \rangle)$ be a nilpotent pseudo-Euclidean Lie algebra.
Then

- 1 If $(\mathfrak{g}, [,], \langle , \rangle)$ is Einstein with $\lambda \neq 0$ then $Z(\mathfrak{g}) \subset [\mathfrak{g}, \mathfrak{g}]$.
- 2 If $\dim Z(\mathfrak{g}) \geq \dim[\mathfrak{g}, \mathfrak{g}]$ then $(\mathfrak{g}, [,], \langle , \rangle)$ is Einstein if and only if it is Ricci flat.

Corollary

Let $(\mathfrak{g}, [,], \langle , \rangle)$ be a 2-nilpotent pseudo-Euclidean Lie algebra.
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Corollary

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Proposition

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be an Einstein Lorentzian nilpotent non abelian Lie algebra. If $[\mathfrak{g}, \mathfrak{g}]$ is non degenerate then it is Lorentzian.

Proof.

Suppose that $[\mathfrak{g}, \mathfrak{g}]$ is nondegenerate Euclidean, choose an orthonormal basis (e_1, \dots, e_d) of $[\mathfrak{g}, \mathfrak{g}]$ and denote by (S_1, \dots, S_d) the associated structure endomorphisms. We have

$$\begin{aligned} \lambda \text{Id}_{\mathfrak{g}} &= -\frac{1}{2} \mathcal{J}_1 + \frac{1}{4} \mathcal{J}_2, \\ \mathcal{J}_1 &= -\sum_{i=1}^d S_i^2, \\ \mathcal{J}_2 u &= -\sum_{i,j=1}^d \langle u, e_i \rangle \text{tr}(S_i \circ S_j) e_j. \end{aligned}$$

Proof.

Since \mathfrak{g} is nilpotent then $\dim[\mathfrak{g}, \mathfrak{g}]^\perp \geq 2$ and we can choose a couple (e, \bar{e}) of isotropic vectors in $[\mathfrak{g}, \mathfrak{g}]^\perp$ such that $\langle e, \bar{e} \rangle = 1$.

So

$$\frac{1}{2}\mathcal{J}_1 e = -\lambda e, \quad \frac{1}{2}\mathcal{J}_1 \bar{e} = -\lambda \bar{e} \quad \text{and} \quad \sum_{i=1}^d \langle S_i e, S_i e \rangle = \sum_{i=1}^d \langle S_i \bar{e}, S_i \bar{e} \rangle = 0.$$

So, according to Lemma 1.1, for any $i \in \{1, \dots, d\}$, $S_i e = \alpha_i e$ and $S_i \bar{e} = -\alpha_i \bar{e}$. Thus

$$\lambda = \frac{1}{2} \sum_{i=1}^d \alpha_i^2 \geq 0.$$

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Proof.

Let $K_i = (S_i)_{|\{e, \bar{e}\}^\perp}$. So $\text{tr}(S_i^2) = 2\alpha_i^2 + \text{tr}(K_i^2)$ and $\text{tr}(K_i^2) \leq 0$.
Now, since $\text{tr}(\mathcal{J}_1) = \text{tr}(\mathcal{J}_2)$, we get

$$(\dim \mathfrak{g})\lambda = -\frac{1}{4}\text{tr}(\mathcal{J}_1) = \frac{1}{4} \sum_{i=1}^d (2\alpha_i^2 + \text{tr}(K_i^2)) = \lambda + \frac{1}{4} \sum_{i=1}^d \text{tr}(K_i^2).$$

This shows that $\lambda = 0$ and $\text{tr}(K_i^2) = 0$ for any i thus $S_i = 0$ which implies that \mathfrak{g} is abelian. This is a contradiction which completes the proof. \square

Proposition

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be an Einstein pseudo-Riemannian non abelian nilpotent Lie algebra of signature $(p, q) = (-, \dots, -, +, \dots, +)$. If $Z(\mathfrak{g})$ is nondegenerate then $Z(\mathfrak{g})^\perp$ is not Euclidean.

Proof.

Suppose that $Z(\mathfrak{g})$ is nondegenerate and $Z(\mathfrak{g})^\perp$ is Euclidean and choose a family of vector $(e_1, \dots, e_p) \in Z(\mathfrak{g})$ such that $\langle e_j, e_j \rangle = -1$. We have $\mathfrak{g} = \text{span}\{e_1, \dots, e_p\} \oplus \mathfrak{g}_0$, where $\mathfrak{g}_0 = \{e_1, \dots, e_p\}^\perp$.
For any $u, v \in \mathfrak{g}_0$, put

$$[u, v] = \sum_{i=1}^p \langle K_i u, v \rangle e_i + [u, v]_0,$$

where $K_i : \mathfrak{g}_0 \rightarrow \mathfrak{g}_0$ are skew-symmetric and $[u, v]_0 \in \mathfrak{g}_0$.

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where $K_i : \mathfrak{g}_0 \rightarrow \mathfrak{g}_0$ are skew-symmetric and $[u, v]_0 \in \mathfrak{g}_0$.

Proof.

It is obvious that $(\mathfrak{g}_0, [,]_0, \langle , \rangle)$ is an Euclidean nilpotent Lie algebra.

We claim that if $(\mathfrak{g}, \langle , \rangle)$ is Einstein then $\lambda = \frac{1}{4}\text{tr}(K_i^2)$, for $i = 1, \dots, p$

$$\text{Ric}_{\langle , \rangle_0} = \lambda \text{Id}_{\mathfrak{g}_0} + \frac{1}{2} \sum_{i=1}^p K_i^2.$$

This implies that the Ricci curvature of $(\mathfrak{g}_0, \langle , \rangle)$ is nonpositive. But a non abelian nilpotent Euclidean Lie algebra has always a Ricci negative direction and Ricci positive direction. So the only possibility is the $K_i = 0$ and \mathfrak{g}_0 is abelian. We get a contradiction which completes the proof. \square

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Corollary

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be an Einstein Lorentzian non abelian nilpotent Lie algebra. If $Z(\mathfrak{g})$ is nondegenerate then it is Euclidean.

Corollary

Let \mathfrak{g} be an Einstein Lorentzian non abelian 2-step nilpotent Lie algebra. Then $Z(\mathfrak{g})$ is degenerate.

Proof.

Suppose that $Z(\mathfrak{g})$ is nondegenerate. According to Proposition 3.5, $Z(\mathfrak{g})$ is nondegenerate Euclidean. But \mathfrak{g} is 2-step nilpotent and hence $[\mathfrak{g}, \mathfrak{g}] \subset Z(\mathfrak{g})$. Thus $[\mathfrak{g}, \mathfrak{g}]$ is nondegenerate Euclidean which contradicts Proposition 3.4. □

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Proposition

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be an Einstein Lorentzian nilpotent Lie algebra such that $[\mathfrak{g}, \mathfrak{g}]$ is degenerate then $[\mathfrak{g}, \mathfrak{g}] \cap [\mathfrak{g}, \mathfrak{g}]^\perp \subset Z(\mathfrak{g})$ and $\lambda = 0$.

Proof.

Let $(e, \bar{e}, f_1, \dots, f_d, g_1, \dots, g_s)$ be a Lorentzian basis of \mathfrak{g} such that (e, f_1, \dots, f_d) is a basis of $[\mathfrak{g}, \mathfrak{g}]$, (e, g_1, \dots, g_s) is a basis of $[\mathfrak{g}, \mathfrak{g}]^\perp$. Denote by (A, S_1, \dots, S_d) the associated structure endomorphisms, i.e., for any $u, v \in \mathfrak{g}$,

$$[u, v] = \langle Au, v \rangle e + \sum_{i=1}^d \langle S_i u, v \rangle f_i.$$

We have

$$-\frac{1}{2}\mathcal{J}_1 + \frac{1}{4}\mathcal{J}_2 = \lambda \text{Id}_{\mathfrak{g}} \quad \text{and} \quad \mathcal{J}_1 = -\sum_{i=1}^d S_i^2.$$

Proposition

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be an Einstein Lorentzian nilpotent Lie algebra such that $[\mathfrak{g}, \mathfrak{g}]$ is degenerate then $[\mathfrak{g}, \mathfrak{g}] \cap [\mathfrak{g}, \mathfrak{g}]^\perp \subset Z(\mathfrak{g})$ and $\lambda = 0$.

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Let $(e, \bar{e}, f_1, \dots, f_d, g_1, \dots, g_s)$ be a Lorentzian basis of \mathfrak{g} such that (e, f_1, \dots, f_d) is a basis of $[\mathfrak{g}, \mathfrak{g}]$, (e, g_1, \dots, g_s) is a basis of $[\mathfrak{g}, \mathfrak{g}]^\perp$. Denote by (A, S_1, \dots, S_d) the associated structure endomorphisms, i.e., for any $u, v \in \mathfrak{g}$,

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Proof.

Since $e \in [\mathfrak{g}, \mathfrak{g}]^\perp$ and isotropic, we have $\mathcal{J}_2 e = 0$, $-\frac{1}{2}\mathcal{J}_1 e = \lambda e$, and hence $\sum_{j=1}^d \langle S_j e, S_j e \rangle = 0$. We get $S_j e = a_j e$ for any $j = 1, \dots, d$ and hence

$$\lambda = \frac{1}{2} \sum_{i=1}^d a_i^2 \geq 0.$$

On the other hand, since $\text{tr}(\mathcal{J}_1) = \text{tr}(\mathcal{J}_2)$, we get

$$(\dim \mathfrak{g})\lambda = -\frac{1}{4}\text{tr}(\mathcal{J}_1) = \frac{1}{4} \sum_{j=1}^d \text{tr}(S_j^2).$$



Proof.

Or

$$\begin{aligned} \operatorname{tr}(S_j^2) &= \langle S_j^2 e, \bar{e} \rangle + \langle S_j^2 \bar{e}, e \rangle + \sum_I \langle S_j^2 f_I, f_I \rangle + \sum_I \langle S_j^2 g_I, g_I \rangle \\ &= 2a_j^2 - \sum_I \langle S_j f_I, S_j f_I \rangle - \sum_I \langle S_j g_I, S_j g_I \rangle. \end{aligned}$$

Thus

$$(\dim \mathfrak{g} - 1)\lambda = - \sum_{I,j} \langle S_j f_I, S_j f_I \rangle - \sum_{I,j} \langle S_j g_I, S_j g_I \rangle.$$



Proof.

Or

$$\begin{aligned} \operatorname{tr}(S_j^2) &= \langle S_j^2 e, \bar{e} \rangle + \langle S_j^2 \bar{e}, e \rangle + \sum_I \langle S_j^2 f_I, f_I \rangle + \sum_I \langle S_j^2 g_I, g_I \rangle \\ &= 2a_j^2 - \sum_I \langle S_j f_I, S_j f_I \rangle - \sum_I \langle S_j g_I, S_j g_I \rangle. \end{aligned}$$

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□

Proof.

Since S_j leaves invariant e , it leaves invariant its orthogonal $\text{span}\{e, f_l, g_k\}$ and hence $\langle S_j f_l, S_j f_l \rangle \geq 0$ and $\langle S_j g_l, S_j g_l \rangle \geq 0$. So $\lambda = 0$, $S_j(e) = 0$. Thus, for any $u \in \mathfrak{g}$, $[e, u] = \langle A(e), u \rangle e$. But ad_u is nilpotent and hence $[e, u] = 0$ which completes the proof. \square

Consider $(V, \langle \cdot, \cdot \rangle_0)$ an Euclidean vector space, $b \in V$, $K, D : V \rightarrow V$ two endomorphisms of V such that K is skew-symmetric. We endow the vector space $\mathfrak{g} = \mathbb{R}e \oplus V \oplus \mathbb{R}\bar{e}$ with the inner product $\langle \cdot, \cdot \rangle$ which extends $\langle \cdot, \cdot \rangle_0$, for which $\text{span}\{e, \bar{e}\}$ and V are orthogonal, $\langle e, e \rangle = \langle \bar{e}, \bar{e} \rangle = 0$ and $\langle e, \bar{e} \rangle = 1$. We define also on \mathfrak{g} the bracket

$$\begin{cases} [\bar{e}, e] = \mu e, \\ [\bar{e}, u] = D(u) + \langle b, u \rangle_0 e, \\ [u, v] = \langle K(u), v \rangle_0 e, \quad u, v \in V. \end{cases} \quad (6)$$

Theorem

- (i) $(\mathfrak{g}, [,]) is a Lie algebra if and only if $KD + D^*K = \mu K$.$
- (ii) *If the condition in (i) is satisfied then $(\mathfrak{g}, \langle , \rangle, [,]) is an Einstein Lorentzian Lie algebra if and only if$*

$$4\mu(\mu + \text{tr}(D)) = \text{tr}(K^2) + 2\text{tr}(D^2) + 2\text{tr}(DD^*).$$

In this case it is Ricci flat.

A data (K, D, μ, b) satisfying the conditions in Theorem 4.1 are called admissible.

Theorem

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be an Einstein nilpotent non abelian Lorentzian Lie algebra and suppose that there exists $e \in Z(\mathfrak{g})$ a central isotropic vector and denote $\mathcal{I} = \mathbb{R}e$. Then:

- ① $Z(\mathfrak{g})$ is degenerate and $\lambda = 0$.
- ② \mathcal{I}^\perp is an ideal and $\mathfrak{g}_0 = \mathcal{I}^\perp / \mathcal{I}$ is an Euclidean abelian Lie algebra.
- ③ \mathfrak{g} is obtained from \mathfrak{g}_0 by the double extension process with admissible data $(K, D, 0, b)$ and D is nilpotent.

Theorem

Let $(\mathfrak{g}, \langle \cdot, \cdot \rangle)$ be an Einstein nilpotent non abelian Lorentzian Lie algebra and suppose that there exists $e \in Z(\mathfrak{g})$ a central isotropic vector and denote $\mathcal{I} = \mathbb{R}e$. Then:

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If $(\mathfrak{g}, [,], \langle , \rangle)$ is a Lorentzian Einstein nilpotent Lie algebra with generate center then \mathfrak{g} is Ricci flat and it is isomorphic to

$$\mathbb{R}\bar{e} \oplus V \oplus \mathbb{R}e$$

with the non vanishing Lie brackets are given by

$$\begin{cases} [\bar{e}, u] = D(u) + \langle b, u \rangle_0 e, \\ [u, v] = \langle K(u), v \rangle_0 e, \quad u, v \in V. \end{cases} \quad (7)$$

K is skew-symmetric and

$$KD + D^*K = 0, \quad D^{\dim V} = 0 \quad \text{and} \quad \text{tr}(K^2) = -2\text{tr}(D^*D).$$

Theorem

Let (G, g) be an Einstein Lorentzian nilpotent Lie group of dimension ≤ 5 . Then the center of \mathfrak{g} is degenerate.

Lie Algebra	Lie brackets	Non Trace-free Derivation
$L_{3,2}$	$[e_1, e_2] = e_3$	$e^1 \otimes e_1 + e^3 \otimes e_3$
$L_{4,2}$	$[e_1, e_2] = e_3$	$e^1 \otimes e_1 + e^3 \otimes e_3$
$L_{4,3}$	$[e_1, e_2] = e_3, [e_1, e_3] = e_4$	$2e^2 \otimes e_2 - e^1 \otimes e_1 + e^3 \otimes e_3$
$L_{5,2}$	$[e_1, e_2] = e_3$	$e^1 \otimes e_1 + e^3 \otimes e_3$
$L_{5,3}$	$[e_1, e_2] = e_3, [e_1, e_3] = e_4$	$2e^2 \otimes e_2 - e^1 \otimes e_1 + e^3 \otimes e_3$
$L_{5,4}$	$[e_1, e_2] = e_5, [e_3, e_4] = e_5$	$e^1 \otimes e_1 + e^3 \otimes e_3 + e^5 \otimes e_5$
$L_{5,5}$	$[e_1, e_2] = e_3, [e_1, e_3] = e_4, [e_2, e_4] = e_5$	$e^3 \otimes e_3 + 2e^2 \otimes e_2 + 2e^5 \otimes e_5 - e^1 \otimes e_1$
$L_{5,6}$	$[e_1, e_2] = e_3, [e_1, e_3] = e_4, [e_1, e_4] = e_5, [e_2, e_3] = e_5$	$e^1 \otimes e_1 + 2e^2 \otimes e_2 + 3e^3 \otimes e_3 + 4e^4 \otimes e_4 + 5e^5 \otimes e_5$
$L_{5,7}$	$[e_1, e_2] = e_3, [e_1, e_3] = e_4, [e_1, e_4] = e_5$	$e^1 \otimes e_1 - 2e^2 \otimes e_2 - e^3 \otimes e_3 + e^5 \otimes e_5$
$L_{5,8}$	$[e_1, e_2] = e_4, [e_1, e_3] = e_5$	$e^1 \otimes e_1 - e^2 \otimes e_2 + e^5 \otimes e_5$
$L_{5,9}$	$[e_1, e_2] = e_3, [e_1, e_3] = e_4, [e_2, e_3] = e_5$	$2e^1 \otimes e_1 - e^2 \otimes e_2 + e^3 \otimes e_3 + 3e^4 \otimes e_4$

Table of nilpotent Lie algebras of dimension ≤ 5 with non null trace derivation

Theorem

Let $(\mathfrak{g}, [,], \langle , \rangle)$ be a Ricci-flat nilpotent Lie algebra of dimension ≤ 5 . Then

- 1 If $\dim \mathfrak{g} = 3$ then \mathfrak{g} is isomorphic to $L_{3,2}$ with the metric $\langle , \rangle_{3,2} = \alpha e_1 \odot e_3 + e_2 \otimes e_2$ with $\alpha > 0$. This metric is actually flat.
- 2 If $\dim \mathfrak{g} = 4$ then \mathfrak{g} is isomorphic to $L_{4,2}$ with the metric

$$\langle , \rangle_{4,2} = \alpha e_1 \odot e_3 + e_2 \otimes e_2 + e_4 \otimes e_4 + b e_2 \odot e_4, \quad \alpha \neq 0, |b| < 1,$$

or to $L_{4,3}$ with the metric

$$\langle , \rangle_{4,3} = e_1 \otimes e_1 + a e_1 \odot e_2 + (a^2 + b^2) e_2 \otimes e_2 + c e_2 \odot e_3 + \varepsilon e_2 \odot e_4 + e_3 \otimes e_3, \quad a, b \in \mathbb{R},$$

$\varepsilon = \pm 1$. The metric $\langle , \rangle_{4,2}$ is flat and $\langle , \rangle_{4,3}$ is flat if and only if $\varepsilon = -1$.

If $\dim \mathfrak{g} = 5$ then \mathfrak{g} is isomorphic to one of the following Lie algebras:

(a) $L_{5,2}$ with the metric

$$\alpha e_1 \odot e_3 + e_2 \otimes e_2 + e_4 \otimes e_4 + e_5 \otimes e_5 + b e_2 \odot e_4 + c e_2 \odot e_5 + b c e_4 \odot e_5,$$

$\alpha \neq 0, |b| < 1, |c| < 1$. This metric is flat.

(b) $L_{5,8}$ with the metric

$$\begin{aligned} & e_1 \otimes e_1 + a e_1 \odot e_2 - y x^{-1} e_1 \odot e_3 + (b - a y x^{-1}) e_2 \odot e_3 + (a^2 + b^2) e_2 \odot e_2 \\ & + \sqrt{x^2 + y^2} e_2 \otimes e_5 + (1 + (y x^{-1})^2) e_3 \otimes e_3 + x^2 e_4 \otimes e_4, \\ & (x \neq 0, a, b, y \in \mathbb{R}). \end{aligned}$$

(c) $L_{5,9}$ with the metric

$$\begin{aligned} & (a^2 + b^2) e_1 \otimes e_1 + (b - a y x^{-1}) e_1 \odot e_2 + a e_1 \odot e_3 + \varepsilon \sqrt{x^2 + y^2 + 1} e_1 \odot e_5 \\ & (1 + (y x^{-1})^2) e_2 \otimes e_2 - y x^{-1} e_2 \odot e_3 + e_3 \otimes e_3 + x^2 e_4 \otimes e_4, \\ & (x \neq 0, a, b, y \in \mathbb{R}). \end{aligned}$$

(d) $L_{5,3}$ with the metric

$$e_1 \otimes e_1 + ae_1 \odot e_2 + (a^2 + b^2)e_2 \otimes e_2 + be_2 \odot e_3 + \varepsilon\sqrt{x^2 + 1}e_2 \odot e_4 \\ + (1 + x^2)e_3 \otimes e_3 - xe_3 \odot e_5 + e_5 \otimes e_5, \quad (x, a, b \in \mathbb{R}).$$

(e) $L_{5,5}$ with the metric

$$(a^2 + b^2)e_1 \otimes e_1 + a\gamma^{-1}e_1 \odot e_2 + \gamma(b - ax^{-1}y)e_1 \odot e_4 + \sqrt{x^2 + y^2}e_1 \odot e_5 \\ + \gamma^{-2}e_2 \otimes e_2 - x^{-1}ye_2 \odot e_4 + x^2\gamma^{-2}e_3 \otimes e_3 + \gamma^2(1 + (x^{-1}y)^2)e_4 \otimes e_4, \\ (x \neq 0, \gamma \neq 0, a, b, y \in \mathbb{R})$$

or

$$e_1 \otimes e_1 + be_1 \odot e_2 + (a^2 + b^2)e_2 \otimes e_2 + ae_2 \odot e_3 + \varepsilon\sqrt{x^2 + 1}e_2 \odot e_5 \\ (1 + x^2)e_3 \otimes e_3 + x\gamma e_3 \odot e_4 + \gamma^2e_4 \otimes e_4, \quad (\gamma \neq 0, x, a, b \in \mathbb{R}).$$

(f) $L_{5,6}$ with the metric

$$(a^2 + b^2)e_1 \otimes e_1 + (b + ax^{-1}y)e_1 \odot e_2 + \mu ae_1 \odot e_3 + \varepsilon\mu^2\sqrt{x^2 + y^2 + 1}e_1 \odot e_5 \\ + (1 + x^{-2}y^2)e_2 \otimes e_2 + \mu x^{-1}ye_2 \odot e_3 + \mu^2e_3 \otimes e_3 + \mu^4x^2e_4 \otimes e_4, \\ \mu \neq 0, \gamma \neq 0, x \neq 0, a, b, y \in \mathbb{R}.$$