

An Introduction to the Geometry of Symmetric Spaces - II -

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A Symmetric Space

$$(M, \{s_x\}_{x \in M})$$

1. $s_x(x) = x$;
2. $s_x \circ s_x = Id_M$;
3. $s_x \circ s_y \circ s_x = s_{s_x(y)}$;
4. $\exists U_x \subseteq M$, such that:

$$\begin{cases} s_x(y) = y; \\ y \in U_x \end{cases} \Rightarrow y = x.$$

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$$(M, \mu)$$

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1. $x \cdot x = x$;
2. $x \cdot (x \cdot y) = y$;
3. $x \cdot (y \cdot z) = (x \cdot y) \cdot (x \cdot z)$;
4. $\exists U_x \subseteq M$, such that:

$$\begin{cases} x \cdot y = y; \\ y \in U_x \end{cases} \Rightarrow y = x.$$

É. Cartan Theorem

Theorem

A pseudo-Riemannian manifold (M, g) is *locally pseudo-Riemannian symmetric* if and only if $\nabla R = 0$, where ∇ is the Levi-Civita connection of g and R its curvature tensor field. If M is *simply-connected* and *complete*, then (M, g) is *pseudo-Riemannian symmetric* if and only if $\nabla R = 0$.

Ambrose-Singer Theorem

Theorem

Let (M, g) be a simply-connected and complete pseudo-Riemannian manifold. The following properties are equivalent:

- 1 (M, g) is reductive homogeneous pseudo-Riemannian manifold.*
- 2 (M, g) admits a linear connection ∇' satisfying*

$$\nabla' g = 0, \quad \nabla' R = 0, \quad \nabla' S = 0,$$

where $S := \nabla - \nabla'$, ∇ the Levi-Civita connection of g , and R its curvature tensor field.

For a proof and other similar theorems, one can see [Calvaruso, G., & López, M. C. \(2019\). Pseudo-Riemannian Homogeneous Structures \(Vol. 59\). New York, NY, USA: Springer.](#)

B. Kostant Theorem ¹

Theorem

Let ∇ be a connection on a simply-connected manifold M . The following properties are equivalent:

- ① M is reductive with respect to a connected Lie subgroup $G \subset \text{Aff}(M, \nabla)$.*
- ② There exists a complete connection ∇' satisfying*

$$\nabla' T = 0, \quad \nabla' R = 0, \quad \nabla' S = 0,$$

where $S := \nabla - \nabla'$, T the torsion of ∇ , and R its curvature tensor field.

¹Kostant, Bertram. "A characterization of invariant affine connections." Nagoya Mathematical Journal 16 (1960): 35-50.

Jordan algebras

A Jordan algebra \mathcal{A} is a finite dimensional vector space with a bilinear multiplication xy satisfying

$$xy = yx, \quad x(x^2y) = x^2(xy),$$

and has a unit element e .

Proposition

The set M of invertible elements of \mathcal{A} is open in \mathcal{A} and becomes a symmetric space with the product

$$\mathfrak{s}_x(y) := 2x(y^{-1}x) - x^2y^{-1}.$$

Main Examples: Symmetric Pairs and Affine Symmetric Spaces

(G, H, σ) a symmetric pair

- $\sigma \in \text{Aut}(G)$ such that:

$$\sigma \circ \sigma = \text{Id}_G,$$

and $\text{Fix}^0(\sigma) \subseteq H \subseteq \text{Fix}(\sigma)$.

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$$(G/H, \mu_\sigma)$$

is a symmetric space, where

$$\bar{a} \cdot \bar{b} := \overline{a\sigma(a^{-1}b)}, \quad \forall a, b \in G.$$

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(M, ∇) an affine symmetric space

- ∇ is a connection and

$$\forall x \in M, \exists! \mathfrak{s}_x \in \text{Aff}(M, \nabla)$$

such that: $\mathfrak{s}_x(\gamma(t)) = \gamma(-t)$,

where $\gamma : (-\varepsilon, \varepsilon) \rightarrow M$ is a geodesic of ∇
and $\gamma(0) = x$.

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and $\gamma(0) = x$.



$$(M, \{\mathfrak{s}_x\}_{x \in M})$$

is a symmetric space.

From Affine Symmetric Spaces to Symmetric Pairs

Let (M, ∇) be an affine symmetric space. Then we have:

- $\text{Aff}^0(M, \nabla)$ acts transitively on M .
- Let $x_0 \in M$ fixed, and denote by H_{x_0} the isotropy group of x_0 in $\text{Aff}^0(M, \nabla)$.
- Define an involutive automorphism of $\text{Aff}^0(M, \nabla)$ by:

$$\sigma^\nabla : \text{Aff}^0(M, \nabla) \rightarrow \text{Aff}^0(M, \nabla), \quad F \mapsto \mathfrak{s}_{x_0} \circ F \circ \mathfrak{s}_{x_0},$$

where $\mathfrak{s}_{x_0} : M \rightarrow M$ is the geodesic symmetry about x_0 .

- The following inclusions hold

$$\text{Fix}^0(\sigma^\nabla) \subseteq H_{x_0} \subseteq \text{Fix}(\sigma^\nabla).$$

In summary:

$$\begin{array}{ccc} (M, \nabla) & \Rightarrow & (\text{Aff}^0(M, \nabla), H_{x_0}, \sigma^\nabla) \\ \text{An affine symmetric space} & & \text{A symmetric pair} \end{array}$$

- The next step: Expression of the canonical connection ∇ associated to a symmetric pair (G, H, σ) ? i.e. G -invariant connection on G/H for which $\bar{\sigma} : G/H \rightarrow G/H$ is an affine map.

Reductive homogeneous G -spaces

A homogeneous G -space G/H is called *reductive* if there exists a vector subspace $\mathfrak{m} \subset \mathfrak{g}$ such that:

$$\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}, \quad \text{and} \quad \text{Ad}(H)(\mathfrak{m}) \subseteq \mathfrak{m},$$

where \mathfrak{g} and \mathfrak{h} are the Lie algebras of G and H respectively.

Remark. Not all homogeneous spaces are reductive.

For example:

$$G := \text{GL}^+(2, \mathbb{R}), \quad \text{and} \quad H := \left\{ \begin{pmatrix} 1 & x \\ 0 & y \end{pmatrix} \mid y > 0, x \in \mathbb{R} \right\}.$$

One can easily check that $G/H \cong \mathbb{R}^2 \setminus \{0\}$ is **not reductive**.

Similarly, not all reductive homogeneous spaces are symmetric. For example the Stiefel manifolds $\mathrm{SO}(n)/\mathrm{SO}(n-k)$ are not symmetric spaces for $2 \leq k \leq n-2$. To see why, consider the matrices $I_{p,q}$ and $J_{n'}$ defined by:

$$I_{p,q} := \begin{pmatrix} I_p & 0 \\ 0 & -I_q \end{pmatrix}, \quad \text{and} \quad J_{n'} := \begin{pmatrix} 0 & -I_{n'} \\ I_{n'} & 0 \end{pmatrix},$$

where $p+q=n$ and $J_{n'}$ is defined only if n is even, in which case $n' := \frac{n}{2}$.

It is known (cf. S. Helgason pp. 453) that up to conjugation, the only involutive automorphisms of $\mathfrak{so}(n)$ are given by:

- $\tau_{p,q}(X) := I_{p,q} X I_{p,q}$, in which case we have

$$\ker(\tau_{p,q} - \text{Id}) \cong \mathfrak{so}(p) \times \mathfrak{so}(q) \neq \mathfrak{so}(n - k).$$

- $\theta(X) := J_{n'} X J_{n'}^T$, in which case we have

$$\ker(\theta - \text{Id}) \cong \mathfrak{u}(n') \neq \mathfrak{so}(n - k).$$

Nomizu Theorem

Theorem

Let $M := G/H$ be a reductive homogeneous G -space with a fixed reductive decomposition, i.e

$$\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}, \quad \text{and} \quad \text{Ad}(H)(\mathfrak{m}) \subseteq \mathfrak{m}.$$

Then there exists a one-to-one correspondence between the set of G -invariant connections on M and the set of bilinear maps $\alpha : \mathfrak{m} \times \mathfrak{m} \rightarrow \mathfrak{m}$ which are $\text{Ad}(H)$ -invariant, i.e

$$\text{Ad}_h \alpha(u, v) = \alpha(\text{Ad}_h u, \text{Ad}_h v),$$

for $u, v \in \mathfrak{m}$ and $h \in H$.

Let $M := G/H$ be a reductive homogeneous G -space with a fixed reductive decomposition $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}$. For each $u \in \mathfrak{g}$, we define a vector field $u^* \in \mathfrak{X}(M)$, called the *fundamental vector field* associated to u by:

$$u_{\bar{a}}^* := \frac{d}{dt} \bigg|_{t=0} \overline{\exp_G(tu)a}, \quad \forall \bar{a} \in M.$$

Moreover, we have a linear isomorphism between \mathfrak{m} and $T_{\bar{e}}M$, given by:

$$\begin{array}{ccc} \mathbf{I}_{\bar{e}} & : & \mathfrak{m} \xrightarrow{\cong} T_{\bar{e}}M \\ & & u \longmapsto u_{\bar{e}}^*. \end{array}$$

If ∇ is a G -invariant connection on M , then its associated bilinear map $\alpha : \mathfrak{m} \times \mathfrak{m} \rightarrow \mathfrak{m}$ is defined as follows²:

$$\alpha(u, v) := \mathbf{I}_{\bar{e}}^{-1} \left((\nabla_{u^*} v^*)_{\bar{e}} \right) + [u, v]_{\mathfrak{m}}.$$

²For $w \in \mathfrak{g}$, we denote by $w_{\mathfrak{m}}$ the projection of w on \mathfrak{m} .

Further, the torsion T^∇ of the G -invariant connection ∇ gives rise to a bilinear map $T^\alpha : \mathfrak{m} \times \mathfrak{m} \rightarrow \mathfrak{m}$ written as

$$T^\alpha(u, v) := \alpha(u, v) - \alpha(v, u) - [u, v]_{\mathfrak{m}}.$$

Hence

Corollary

Let ∇ be a G -invariant connection on M and α its associated bilinear map. Then ∇ is torsion-free if and only if for any $u, v \in \mathfrak{m}$

$$\alpha(u, v) = \frac{\alpha(u, v) + \alpha(v, u)}{2} + \frac{1}{2}[u, v]_{\mathfrak{m}},$$

i.e. the bilinear map $\alpha_{\text{sym}}(u, v) := \alpha(u, v) - \frac{1}{2}[u, v]_{\mathfrak{m}}$ is symmetric.

Particular G -invariant connections on M

- The natural connection ∇^0 given by:

$$\alpha^0(u, v) = \frac{1}{2}[u, v]_{\mathfrak{m}}, \quad \forall u, v \in \mathfrak{m}.$$

It is **torsion-free**.

- The canonical connection ∇^c given by:

$$\alpha^c(u, v) = 0, \quad \forall u, v \in \mathfrak{m}.$$

It is invariant under parallelism i.e the torsion and the curvature tensors of ∇^c are both parallel.

Remark. $\nabla^c = \nabla^0$ if and only if $[\mathfrak{m}, \mathfrak{m}] \subseteq \mathfrak{h}$.

Nomizu's Theorem allows us to transfer geometric conditions to algebra, or algebraic conditions to geometry.

Proposition

Let $M := G/H$ be a reductive homogeneous G -space with a fixed reductive decomposition $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}$ and ∇ a G -invariant connection on M with $\alpha : \mathfrak{m} \times \mathfrak{m} \rightarrow \mathfrak{m}$ its associated bilinear map. For each $u \in \mathfrak{m}$, we have

$$\alpha(u, u) = 0 \quad \Leftrightarrow \quad t \mapsto \overline{\exp_G(tu)} \text{ is a geodesic of } \nabla.$$

Proof. Let $u \in \mathfrak{m}$ and $\gamma : \mathbb{R} \rightarrow M$, $t \mapsto \overline{\exp_G(tu)}$. Since $\dot{\gamma}(t) = u_{\gamma(t)}^*$, then a direct computation yields

$$\nabla_{\dot{\gamma}} \dot{\gamma}(t) = \left(\lambda_{\exp_G(tu)} \right)_* \alpha(u, u)_{\bar{e}}^*. \quad \blacksquare$$

Notice that if ∇ is a G -invariant connection on M whose geodesics through \bar{e} are exactly the curves $t \mapsto \overline{\exp_G(tu)}$ for any $u \in \mathfrak{m}$, then the geodesics through another point \bar{a} of M are exactly the curves $t \mapsto \overline{\exp_G(t\text{Ad}_a u)a}$, with $u \in \mathfrak{m}$.

Corollary

On a reductive homogeneous G -space $M := G/H$ with a fixed reductive decomposition $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}$, the natural connection ∇^0 is the only G -invariant torsion-free connection whose geodesics are exactly the curves $t \mapsto \overline{\exp_G(t\text{Ad}_a u)a}$, with $u \in \mathfrak{m}$ and $\bar{a} \in M$.

Example. A connected Lie group G , viewed as a reductive homogeneous $(G \times G)$ -space, endowed with its natural bi-invariant connection!

From Symmetric Pairs to Affine Symmetric Spaces

Theorem

Let (G, H, σ) be a symmetric pair, then $M := G/H$ is an affine symmetric space.

Proof. Let $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}$ be the canonical decomposition of \mathfrak{g} and ∇^0 the natural torsion-free G -invariant connection on M associated to the bilinear map $\alpha^0 \equiv 0$. Consider the following smooth map on M

$$\mathfrak{s}^0 : M \rightarrow M, \quad \bar{a} \mapsto \overline{\sigma(a)}.$$

This is well defined because $H \subseteq \text{Fix}(\sigma)$, and satisfies

$$\mathfrak{s}^0 \circ \mathfrak{s}^0 = \text{Id}_M.$$

Proof. $\mathfrak{s}^0 \in \text{Aff}(M, \nabla^0)$

Define a connection ∇ on M by:

$$\nabla_X Y := \mathfrak{s}_*^0 \left(\nabla_{\mathfrak{s}_*^0 X}^0 \mathfrak{s}_*^0 Y \right), \quad \forall X, Y \in \mathfrak{X}(M).$$

Let us show that $\nabla = \nabla^0$. First, for each $a \in G$, we have the following commutative diagram

$$\begin{array}{ccc} M & \xrightarrow{\mathfrak{s}^0} & M \\ \lambda_a \downarrow & & \downarrow \lambda_{\sigma(a)} \\ M & \xrightarrow{\mathfrak{s}^0} & M \end{array} .$$

Thus ∇ is G -invariant. Let α be its associated bilinear map.

Proof. $\mathfrak{s}^0 \in \text{Aff}(M, \nabla^0)$

For each $u \in \mathfrak{m}$ and $a \in G$ we have

$$\begin{aligned} (\mathfrak{s}_*^0 u^*)_{\bar{a}} &= \frac{d}{dt} \Big|_{t=0} \mathfrak{s}^0 \left(\overline{\exp_G(tu) \sigma(a)} \right) \\ &= \frac{d}{dt} \Big|_{t=0} \overline{\exp_G(-tu) a} \\ &= -u_{\bar{a}}^*. \end{aligned}$$

Thus

$$\mathfrak{s}_*^0 u^* = -u^*, \quad \forall u \in \mathfrak{m}.$$

Proof. $\mathfrak{s}^0 \in \text{Aff}(M, \nabla^0)$

Hence for $u, v \in \mathfrak{m}$ we have

$$\begin{aligned}\alpha(u, v) &= I_{\bar{e}}^{-1} \left((\nabla_{u^*} v^*)_{\bar{e}} \right) \\ &= I_{\bar{e}}^{-1} \left(s_*^0 (\nabla_{u^*}^0 v^*)_{\bar{e}} \right) \\ &= -I_{\bar{e}}^{-1} \left(\alpha^0(u, v)_{\bar{e}}^* \right) \\ &= 0,\end{aligned}$$

which implies that $\nabla = \nabla^0$ and therefore $\mathfrak{s}^0 \in \text{Aff}(M, \nabla^0)$.

Proof. \mathfrak{s}^0 is a geodesic symmetry about \bar{e}

Now it only remains to check that \mathfrak{s}^0 is a geodesic symmetry about \bar{e} . Let $t \mapsto \overline{\exp_G(tu)}$ be a geodesic through \bar{e} with $u \in \mathfrak{m}$, then

$$\begin{aligned}\mathfrak{s}^0\left(\overline{\exp_G(tu)}\right) &= \overline{\sigma(\exp_G(tu))} \\ &= \overline{\exp_G(-tu)}.\end{aligned}$$

Thus \mathfrak{s}^0 is a geodesic symmetry about \bar{e} .

Finally, for any $\bar{a} \in M$ we define the geodesic symmetry about \bar{a} as follow

$$\begin{array}{ccc} M & \xrightarrow{\mathfrak{s}^0} & M \\ \lambda_{a^{-1}} \uparrow & & \downarrow \lambda_a \\ \textcolor{blue}{M} & \xrightarrow{\textcolor{blue}{\mathfrak{s}_{\bar{a}}}} & \textcolor{blue}{M}. \end{array}$$

One can check easily that $\mathfrak{s}_{\bar{a}}$ satisfies all the conditions required for a geodesic symmetry. ■

(G, H, σ)
A symmetric pair



$(G/H, \nabla^0)$
An affine symmetric space

Invariant Pseudo-Riemannian Metrics on a Reductive Homogeneous G -space

Theorem

Let $M := G/H$ be a reductive homogeneous G -space with a fixed reductive decomposition $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}$. There is a natural one-to-one correspondence between the set of G -invariant pseudo-Riemannian metrics on M and the set of $\text{Ad}(H)$ -invariant non-degenerate symmetric bilinear forms on \mathfrak{m} .

For the sake of simplicity, we shall use the same notation $\langle \cdot, \cdot \rangle$ to denote both the G -invariant pseudo-Riemannian metric on M , and its associated $\text{Ad}(H)$ -invariant non-degenerate symmetric bilinear form on \mathfrak{m} .

Proposition

Let $M := G/H$ be a reductive homogeneous G -space with a fixed reductive decomposition $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}$, and let $\langle \cdot, \cdot \rangle$ be a G -invariant pseudo-Riemannian metric on M . The Levi-Civita connection ∇^{LC} of $\langle \cdot, \cdot \rangle$ is G -invariant and its associated bilinear map $\alpha^{\text{LC}} : \mathfrak{m} \times \mathfrak{m} \rightarrow \mathfrak{m}$ is given by:

$$\alpha^{\text{LC}}(u, v) := \frac{1}{2}[u, v]_{\mathfrak{m}} + \alpha_{\text{sym}}^{\text{LC}}(u, v),$$

where $\alpha_{\text{sym}}^{\text{LC}} : \mathfrak{m} \times \mathfrak{m} \rightarrow \mathfrak{m}$ is the symmetric bilinear map defined by:

$$\langle \alpha_{\text{sym}}^{\text{LC}}(u, v), w \rangle = \frac{1}{2} \left\{ \langle [w, u]_{\mathfrak{m}}, v \rangle + \langle u, [w, v]_{\mathfrak{m}} \rangle \right\},$$

for all $u, v, w \in \mathfrak{m}$.

Proof. A direct computation using Koszul's formula shows that ∇^{LC} is G -invariant. Moreover, for $u, v, w \in \mathfrak{m}$ we have

$$\begin{aligned}
\langle \alpha^{\text{LC}}(u, v), w \rangle &= \langle \nabla_{u^*}^{\text{LC}} v^*, w^* \rangle_{\bar{e}} + \langle [u, v]^*, w^* \rangle_{\bar{e}} \\
&= \frac{1}{2} \left\{ \langle [u, v]^*, w^* \rangle_{\bar{e}} + \langle [w, u]^*, v^* \rangle_{\bar{e}} + \langle u^*, [w, v]^* \rangle_{\bar{e}} \right\} \\
&= \frac{1}{2} \left\{ \langle [u, v]_{\mathfrak{m}}, w \rangle + \langle [w, u]_{\mathfrak{m}}, v \rangle + \langle u, [w, v]_{\mathfrak{m}} \rangle \right\} \\
&= \left\langle \frac{1}{2} [u, v]_{\mathfrak{m}} + \alpha_{\text{sym}}^{\text{LC}}(u, v), w \right\rangle,
\end{aligned}$$

where

$$\langle \alpha_{\text{sym}}^{\text{LC}}(u, v), w \rangle := \frac{1}{2} \left\{ \langle [w, u]_{\mathfrak{m}}, v \rangle + \langle u, [w, v]_{\mathfrak{m}} \rangle \right\}. \quad \blacksquare$$

Corollary

With the notations of the previous proposition, The Levi-Civita connection ∇^{LC} of $\langle \cdot, \cdot \rangle$ coincides with the natural connection ∇^0 associated to the decomposition $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}$ if and only if

$$\langle [u, v]_{\mathfrak{m}}, w \rangle + \langle v, [u, w]_{\mathfrak{m}} \rangle = 0, \quad \forall u, v, w \in \mathfrak{m}.$$

Corollary

Let (G, H, σ) be a symmetric pair. A G -invariant pseudo-Riemannian metric on G/H , if there exists any, induces the canonical connection.

Semi-simple Lie Algebras

Definition

Let $(\mathfrak{g}, [\cdot, \cdot])$ be a Lie algebra.

- \mathfrak{g} is *simple* if it is nonabelian and does not contain any ideal distinct from $\{0\}$ and \mathfrak{g} .
- \mathfrak{g} is *semi-simple* if does not contain any nonzero solvable ideal. (\mathfrak{a} is solvable i.e. there exists n s.t. $\mathcal{D}^n(\mathfrak{a}) = \{0\}$).

Let $(\mathfrak{g}, [\cdot, \cdot])$ be a Lie algebra. Then the following statements are equivalent:

1. \mathfrak{g} is semi-simple.
2. $\mathfrak{g} = \mathfrak{g}_1 \oplus \cdots \oplus \mathfrak{g}_r$, where the \mathfrak{g}_i 's are ideals of \mathfrak{g} which are simple (as Lie algebras).
3. \mathfrak{g} has no nonzero abelian ideal.
4. The Killing form $B_{\mathfrak{g}} : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathbb{R}$ of \mathfrak{g} is non-degenerate.

Cartan involution

Let $\tau : \mathfrak{g} \rightarrow \mathfrak{g}$ be an automorphism with $\tau^2 = \text{Id}_{\mathfrak{g}}$. Then, the bilinear form

$$B^\tau(u, v) := -B_{\mathfrak{g}}(u, \tau(v)),$$

is symmetric, where $B_{\mathfrak{g}}$ is the Killing form of \mathfrak{g} . τ is called a *Cartan involution* if B^τ is an inner product on \mathfrak{g} .

Proposition

$\theta(A) := -A^t$ is an involution of $M_n(\mathbb{R})$. If $\mathfrak{g} \subset M_n(\mathbb{R})$ is a subalgebra such that

$$\theta(\mathfrak{g}) \subset \mathfrak{g}, \quad \text{and} \quad Z(\mathfrak{g}) = \{0\},$$

then, $\tau := \theta|_{\mathfrak{g}}$ is a Cartan involution of \mathfrak{g} .

It is the case, for example, of the subalgebras $\mathfrak{sl}(n, \mathbb{R})$ and $\mathfrak{so}(p, q)$.

Proof. We have to show that for any $X \in \mathfrak{g}$, s.t. $X \neq 0$

$$B^T(X, X) = \text{tr}(\text{ad}_X \circ \text{ad}_{X^t}) > 0 \quad ?$$

Consider the canonical inner product on \mathfrak{g} :

$$\langle X, Y \rangle := \text{tr}(X^t Y),$$

this induces an inner product on $\text{End}(\mathfrak{g})$:

$$\langle \langle f_1, f_2 \rangle \rangle := \text{tr}(f_1^T \circ f_2),$$

where $f_1^T : \mathfrak{g} \rightarrow \mathfrak{g}$ is the transpose defined through $\langle \cdot, \cdot \rangle$.

A small computation shows that $\text{ad}_{X^t} = (\text{ad}_X)^T$. ■

Theorem

Let (G, H, σ) be a symmetric pair such that G is semi-simple. Then the canonical connection on G/H is induced by a G -invariant pseudo-Riemannian metric. If moreover σ' is a Cartan involution, then the canonical connection on G/H is induced by a G -invariant Riemannian metric.

Proof. Define an $\text{Ad}(H)$ -invariant symmetric bilinear form on \mathfrak{m} by:

$$\langle \cdot, \cdot \rangle : \mathfrak{m} \times \mathfrak{m} \rightarrow \mathbb{R}, \quad \text{written} \quad \langle u, v \rangle := -B_{\mathfrak{g}}(u, v),$$

where $B_{\mathfrak{g}} : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathbb{R}$ is the Killing form of \mathfrak{g} . Furthermore, since \mathfrak{g} is semi-simple and $B_{\mathfrak{g}}(\mathfrak{h}, \mathfrak{m}) = 0$, we deduce that $\langle \cdot, \cdot \rangle$ is non-degenerate. ■

Irreducible Symmetric Spaces

In what follows, (G, H, σ) will be a symmetric pair, $\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{h}$ the canonical decomposition of \mathfrak{g} corresponding to σ , and

$$\mathrm{ad}^{\mathfrak{m}} : \mathfrak{h} \rightarrow \mathrm{End}(\mathfrak{m}), \quad u \mapsto [u, \cdot],$$

the adjoint representation of \mathfrak{h} in \mathfrak{m} . Moreover, we put $M := G/H$ and we assume that the action of G on M is almost effective, i.e. the representation $\mathrm{ad}^{\mathfrak{m}} : \mathfrak{h} \rightarrow \mathrm{End}(\mathfrak{m})$ is injective.

Definition

M is called *irreducible* if $\mathrm{ad}^{\mathfrak{m}} : \mathfrak{h} \rightarrow \mathrm{End}(\mathfrak{m})$ is irreducible.

Proposition (1)

If M is irreducible, then either

$$\mathfrak{g} \text{ is semi-simple,} \quad \text{or} \quad [\mathfrak{m}, \mathfrak{m}] = \{0\}.$$

Proof. Let $\mathfrak{m}' := \text{rad}(B_{\mathfrak{g}}) \cap \mathfrak{m}$. It is clear that \mathfrak{m}' is an \mathfrak{h} -submodule of \mathfrak{m} and hence either $\mathfrak{m}' = \{0\}$ or $\mathfrak{m}' = \mathfrak{m}$.

1. **If $\mathfrak{m}' = \{0\}$:** We shall prove that \mathfrak{g} is semi-simple. Let $u \in \text{rad}(B_{\mathfrak{g}})$, then write $u = u_{\mathfrak{m}} + u_{\mathfrak{h}}$ for $u_{\mathfrak{m}} \in \mathfrak{m}$ and $u_{\mathfrak{h}} \in \mathfrak{h}$. Since $B_{\mathfrak{g}}(\mathfrak{h}, \mathfrak{m}) = 0$, we have for $v \in \mathfrak{m}$

$$B_{\mathfrak{g}}(u_{\mathfrak{m}}, v) = B_{\mathfrak{g}}(u, v) = 0.$$

Thus $u_{\mathfrak{m}} \in \mathfrak{m}' = \{0\}$ and therefore $u \in \mathfrak{h} \cap \text{rad}(B_{\mathfrak{g}})$. Hence $[u, v] = 0$ for all $v \in \mathfrak{m}$. Now, using the fact that $\text{ad}^{\mathfrak{m}} : \mathfrak{h} \rightarrow \text{End}(\mathfrak{m})$ is injective we deduce that $u = 0$, and it follows that \mathfrak{g} is semi-simple.

2. **If $\mathfrak{m}' = \mathfrak{m}$:** In this case we have $\mathfrak{m} \subseteq \text{rad}(B_{\mathfrak{g}})$. Recall that a **nil ideal** of \mathfrak{g} is an ideal \mathfrak{n} of \mathfrak{g} such that ad_u is nilpotent for all $u \in \mathfrak{n}$. We denote by $\text{nilrad}(\mathfrak{g})$ the unique maximal nil ideal of \mathfrak{g} , then the following inclusion holds³

$$[\mathfrak{g}, \text{rad}(\mathfrak{g})] \subseteq \text{nilrad}(\mathfrak{g}).$$

Hence, we have

$$\mathfrak{m} = [\mathfrak{h}, \mathfrak{m}] \subseteq [\mathfrak{h}, \text{rad}(B_{\mathfrak{g}})] \subseteq [\mathfrak{g}, \text{rad}(\mathfrak{g})] \subseteq \text{nilrad}(\mathfrak{g}).$$

Since $\text{nilrad}(\mathfrak{g})$ is nilpotent, there exists a positive integer k such that $\text{nilrad}(\mathfrak{g})^k = \{0\}$ and therefore $\mathfrak{m}^k = \{0\}$. If $k = 1$ then we are done. Suppose that $k \geq 2$ and k is odd, then it is clear that \mathfrak{m}^{k-1} is an \mathfrak{h} -submodule of \mathfrak{m} .

³For more details about $\text{rad}(\mathfrak{g})$ and $\text{nilrad}(\mathfrak{g})$, we refer the interested reader to the book of V.S. Varadarajan (Ref.).

Thus either

$$\mathfrak{m}^{k-1} = \mathfrak{m}, \quad \text{or} \quad \mathfrak{m}^{k-1} = \{0\}.$$

In the first case, we get

$$[\mathfrak{m}, \mathfrak{m}] = [\mathfrak{m}, \mathfrak{m}^{k-1}] = \mathfrak{m}^k = \{0\}.$$

In the second case, we have

$$[\mathfrak{m}^{k-2}, \mathfrak{m}] = \mathfrak{m}^{k-1} = \{0\}.$$

Since $\mathfrak{m}^{k-2} \subset \mathfrak{h}$ and $\text{ad}^{\mathfrak{m}} : \mathfrak{h} \rightarrow \text{End}(\mathfrak{m})$ is injective we get that $\mathfrak{m}^{k-2} = \{0\}$. This argument shows that

$$[\mathfrak{m}, \mathfrak{m}] = \{0\}. \quad \blacksquare$$

Proposition (2)

If \mathfrak{g} is semi-simple, then $[\mathfrak{m}, \mathfrak{m}] = \mathfrak{h}$.

Proof. It is straightforward to see that $[\mathfrak{m}, \mathfrak{m}] \neq \{0\}$, because otherwise \mathfrak{m} will be an abelian ideal of \mathfrak{g} . Moreover, we can easily check that $\mathfrak{m} \oplus [\mathfrak{m}, \mathfrak{m}]$ is an ideal of \mathfrak{g} and therefore since \mathfrak{g} is semi-simple, there exists a supplementary ideal $\mathfrak{a} \subset \mathfrak{g}$ such that

$$\mathfrak{g} = \mathfrak{m} \oplus [\mathfrak{m}, \mathfrak{m}] \oplus \mathfrak{a}.$$

We will prove that $\mathfrak{a} = \{0\}$. Using that $\text{ad}^{\mathfrak{m}} : \mathfrak{h} \rightarrow \text{End}(\mathfrak{m})$ is injective, it is sufficient to show that \mathfrak{a} is contained in \mathfrak{h} . Let $u \in \mathfrak{a}$, then write $u = u_{\mathfrak{m}} + u_{\mathfrak{h}}$ for $u_{\mathfrak{m}} \in \mathfrak{m}$ and $u_{\mathfrak{h}} \in \mathfrak{h}$.

For $v \in \mathfrak{m}$ one has

$$\underbrace{[u, v]}_{\in \mathfrak{a}} = \underbrace{[u_{\mathfrak{m}}, v]}_{\in [\mathfrak{m}, \mathfrak{m}]} + \underbrace{[u_{\mathfrak{h}}, v]}_{\in \mathfrak{m}}.$$

Thus $[u_{\mathfrak{m}}, v] = [u, v] = [u_{\mathfrak{h}}, v] = 0$. Similarly, for $v \in [\mathfrak{m}, \mathfrak{m}]$ we have

$$\underbrace{[u, v]}_{\in \mathfrak{a}} = \underbrace{[u_{\mathfrak{m}}, v]}_{\in \mathfrak{m}} + \underbrace{[u_{\mathfrak{h}}, v]}_{\in [\mathfrak{m}, \mathfrak{m}]}.$$

Hence $[u_{\mathfrak{m}}, v] = [u, v] = [u_{\mathfrak{h}}, v] = 0$. Let $v \in \mathfrak{g}$ and write $v = v_{\mathfrak{m}} + v_{[\mathfrak{m}, \mathfrak{m}]} + v_{\mathfrak{a}}$ for $v_{\mathfrak{m}} \in \mathfrak{m}$, $v_{[\mathfrak{m}, \mathfrak{m}]} \in [\mathfrak{m}, \mathfrak{m}]$, $v_{\mathfrak{a}} \in \mathfrak{a}$, then

$$[u_{\mathfrak{m}}, v] = [u_{\mathfrak{m}}, v_{\mathfrak{m}}] + [u_{\mathfrak{m}}, v_{[\mathfrak{m}, \mathfrak{m}]}] + [u_{\mathfrak{m}}, v_{\mathfrak{a}}] = 0.$$

Thus $u_{\mathfrak{m}} \in Z(\mathfrak{g}) = \{0\}$, and it follows that $u = u_{\mathfrak{h}} \in \mathfrak{h}$. ■

Irreducible Symmetric Spaces

Theorem

Let $M := G/H$ be an *irreducible* symmetric space where the action of G on M is effective and \mathfrak{g} is *semi-simple*. Then $\text{Aff}^0(M, \nabla^0) = G$.

Proof. First, since the action is effective, we can identify G and H with their images under the homogeneous action λ :

$$G \cong \lambda(G) \subseteq G^1 := \text{Aff}^0(M, \nabla^0),$$

then $H \subseteq H^1 := G^1_{\bar{e}}$, the isotropy group of \bar{e} in G^1 . Let $\mathfrak{g}^1 = \mathfrak{m}^1 \oplus \mathfrak{h}^1$ be the canonical decomposition of the symmetric pair (G^1, σ^1, H^1) , where $\sigma^1(f) = \bar{\sigma} \circ f \circ \bar{\sigma}$.

Moreover, we have the following commutative diagram:

$$\begin{array}{ccc} G^1 & \xrightarrow{\sigma^1} & G^1 \\ \uparrow \iota & & \uparrow \iota \\ G & \xrightarrow{\sigma} & G, \end{array}$$

where $\iota : G \hookrightarrow G^1$ is the canonical injection. This implies $\mathfrak{m} \subseteq \mathfrak{m}^1$ and $\mathfrak{h} \subseteq \mathfrak{h}^1$. But since $M = G/H = G^1/H^1$ we have $\mathfrak{m} = \mathfrak{m}^1$. Then, $\mathfrak{h}^1 \rightarrow \text{End}(\mathfrak{m}^1)$ is irreducible because $\mathfrak{h} \subseteq \mathfrak{h}^1$. Now, \mathfrak{g} is semi-simple, then $\mathfrak{h} = [\mathfrak{m}, \mathfrak{m}] = [\mathfrak{m}^1, \mathfrak{m}^1]$, which implies (Proposition (1)) \mathfrak{g}^1 is semi-simple, and therefore $[\mathfrak{m}, \mathfrak{m}] = \mathfrak{h}^1$ (Proposition (2)). Thus $\mathfrak{h} = \mathfrak{h}^1$, which proves that $\mathfrak{g}^1 = \mathfrak{g}$ and finally $G^1 = G$. ■

Corollary

Let $(M := G/H, \langle \cdot, \cdot \rangle)$ be an *irreducible* (pseudo)Riemannian symmetric space where G is effective on M and \mathfrak{g} is *semi-simple*. Then $G = \text{Iso}^0(M, \langle \cdot, \cdot \rangle) = \text{Aff}^0(M, \nabla^0)$.

Now we return to our question:

Given a symmetric space (M, μ) , how can we define directly from μ a torsion-free connection on M such that it becomes an affine symmetric space?

The answer is complicated, so we will just sketch out the idea.

Starting from a symmetric space (M, μ) , we will construct a torsion-free connection on M . But first we need to introduce some constructions.

Let $F \in C^\infty(M \times M)$ be a smooth function. For each $x \in M$ we define two smooth functions $F_x^\ell, F_x^r \in C^\infty(M)$ by:

$$F_x^\ell(y) := F(x, y), \quad \text{and} \quad F_x^r(y) := F(y, x).$$

We can use this to associated to each vector field $X \in \mathfrak{X}(M)$, two vector fields $X_\ell, X_r \in \mathfrak{X}(M \times M)$, defining they action on an arbitrary smooth fuction $F \in C^\infty(M \times M)$ by:

$$(X_\ell F)(x, y) := (X F_x^\ell)(y), \quad \text{and} \quad (X_r F)(x, y) := (X F_y^r)(x).$$

Let $X, Y \in \mathfrak{X}(M)$, the construction above allows us to define an operator

$$X \cdot Y : C^\infty(M) \rightarrow C^\infty(M),$$

by setting

$$(X \cdot Y)f := X_r Y_\ell (f \circ \mu) \circ \Delta,$$

where $\mu : M \times M \rightarrow M$ is the multiplication map and

$$\Delta : M \rightarrow M \times M, \quad x \mapsto (x, x),$$

is the diagonal mapping.

Lemma

Let (U, x^i) be a local chart of M centered at $x_0 \in M$, and $X, Y \in \mathfrak{X}(M)$ two vector fields on M . Then if we write $X = X^i \partial_{x^i}$ and $Y = Y^j \partial_{x^j}$ on U , we have

$$XY = X^i Y^j \frac{\partial^2}{\partial x^i \partial x^j} + X^i \frac{\partial Y^j}{\partial x^i} \frac{\partial}{\partial x^j},$$

and

$$\frac{1}{2} X \cdot Y = -X^i Y^j \frac{\partial^2}{\partial x^i \partial x^j} + \Gamma_{ij}^k \frac{\partial}{\partial x^k},$$

where Γ_{ij}^k are smooth functions defined on U .

The Canonical Connection on Symmetric Spaces

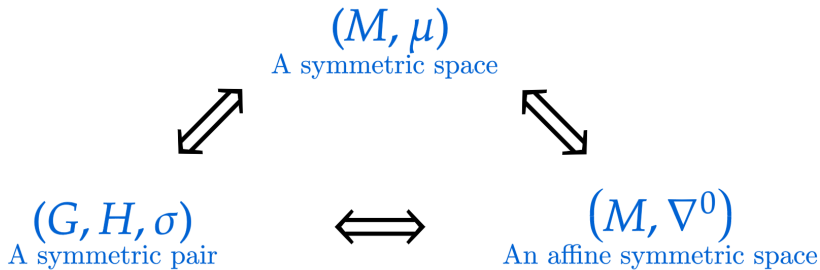
Theorem

Let $(M, \{\mathfrak{s}_x\}_{x \in M})$ be a symmetric space, then there exists a unique torsion-free connection on M such that each involution \mathfrak{s}_x is a geodesic symmetry about x .

Sketch of the Proof. For $X, Y \in \mathfrak{X}(M)$, we define

$$\nabla_X^0 Y := XY + \frac{1}{2}X \cdot Y. \quad \blacksquare$$

For a full proof one can see [Loos, Ottmar. *Symmetric spaces: General theory*. Vol. 1. WA Benjamin, 1969.](#)








Example: Lie groups




Let G be a connected Lie group and \mathfrak{g} its Lie algebra. Then

$$\begin{array}{ccc} & (G, \mu) & \\ \nearrow & a \cdot b := ab^{-1}a & \nwarrow \\ & \forall a, b \in G & \\ (G \times G, \Delta G, \sigma) & \longleftrightarrow & (G, \nabla^0) \\ \sigma(a, b) := (b, a) & & \nabla_{u^+}^0 v^+ := \frac{1}{2}[u^+, v^+] \\ \forall a, b \in G & & \forall u, v \in \mathfrak{g} \end{array}$$

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